Specifications of Bipolar Driver Circuit Board BD202412-S

- For Ringpump RP-S06 / RP-2S06 / RP-WII04 series -

1. Power supply voltage			DC 24V					
2. Drive system			Limited to Quarter (1/4) steps					
3. Output current			1.6A	Quarter Step Drive Waveform (CLK: 2400Hz) Iz)				
			Applicable Stepper Motor :		NKM-1 NKM-1 NKM-1	7D60A4 7D80A4 7D80A4	for Ringpump RP-SOG for Ringpump RP-2SO for Ringpump RP-W I	5 series)6 series I series
4. CW/CCW switchi	ing		High = CWLow = CCWSelect High when the voltage is higher than 2.0V and lower than 5.0V.Select Low when the voltage is lower than 0.8V.					
5. Start/Stop			High = Start Low = Stop Select High when the voltage is higher than 2.0V and lower than 5.0V. Select Low when the voltage is lower than 0.8V.					
6. Driver IC BE	06372	5BEFV	(ROHm)					
			BD63XXXEFV GND 1 VCC1 OUT1B 2 4 2 4 4 RNF1 3 4 4 RNF1 3 4 4 RNF1 4 4 OUT1A 5 7 Control log NC 8 Blank time PWM control NC 7 Control log NC 8 Blank time PWM control NC 7 Control log NC 8 PWM control NC 7 Control log NC 8 PWM control NC 7 Control log NC 7 Control log NC 8 PWM control NC 7 Control log NC 7 Control log NC 8 PWM control NC 7 Control log NC 7 Control log NC 8 PWM control NC 7 Control log NC 8 PWM control NC 7 Control log NC 7 Control log NC 8 PWM control NC 7 Control log NC 7 Control log NC 7 Control log NC 8 PWM control NC 7 Control log NC 8 PWM control NC 7 Control log NC 7 Control log NC 7 Control log NC 7 Control log NC 8 PWM control NC 8 PWM control NC 7 Control log NC 8 PWM control NC 8 PWM contro		28 27 26 25 24 23 23 23 22 20 100 10 10 10 11 15 15 15 15 15 15 15 15 15	NC OUT2B RNF2 RNF2S OUT2A NC VCC2 NC ENABLE MODE1 MODE1 MODE0 TEST/TEST1 CW_CCW CLK	L	
F	Terminal	Name	Figure 2 Driver	Terminal	Name		Function	
Ī	Number 1	GND	Ground Terminal	Number 15	CLK	Phase-Forw	ard Clock Input Terminal	
-	2	OUT1B	H-bridge output terminal	16	CW_CCW TEST	Motor rotation	on direction setting terminal Il (used by connecting to GND)	
-	3		Current-sense comparator input terminal	1/*1	TEST1	Test termina Motor excita	al	
-	5	OUT1A	H-bridge output terminal	19	MODE1	Motor excita	tion mode setting terminal	
F	6	NC VCC1	Non-connection Power Terminal	20	ENABLE	Output Enab	le Terminal	
-	8	NC	Non-connection	22	VCC2	Power Term	inal	
	9	GND	Ground Terminal	23	NC	Non-connec	tion	
=	10	CR NC	Chopping frequency setting terminal Non-connection	24	OUT2A	H-bridge out	put terminal	
	11*1	TEST0	Test terminal	25	RNF2S	Current-sen:	se comparator input terminal	
-	12	MTH	Current attenuation method setting terminal	26	RNF2	Resister con	nection terminal for current sensing	
13 VREF Output current value 14 PS Power Save Terminal		Power Save Terminal	27	NC	Non-connec	put terminal		

* 1 : Upper row BD63715AEFV, BD63725BEFV, BD63525AEFV

7. Clock terminal

Duty : 50%

Select High when the voltage is higher than 2.8V and lower than 5.0V.

Select Low when the voltage is lower than 0.6V.

RP-S06 * -600Z-DC24VS / RP-2S06 * -1300Z-DC24VS / RP-W II 04F-700Z-DC24VS Continuous Driving Max : 3333Hz 833PPS 250rpm

Frequency (Hz)	40	400	1000	2000	2400	2800	3333	4000
PPS	10	100	250	500	600	700	833	1000
Rotation (rpm)	3	30	75	150	180	210	250	300

* If it is more than 250 rpm, increase the rotation speed from about 210 rpm to prevent loss of synchronism.

ON time Max 30min. **ON : OFF** time=1:1

8. Optical terminal

DC5.0V 15mA Output terminal (CN2 ⑤Pin)

9. Explanation of Bi-polar Driver Board BD202412-S 70 x 80□



Board-side male connector **B*B-XH-A Series/JST**

Connection-side female connector XHP* Series/JST Contact Pin BXH-001T-P0.6

> CV O-CCW ON SW2 O-

CN1	Stepper mo	tor connect		
	1	B +	Red	
	2	В—	Blue	
	3	A +	Black	
	4	Α-	Green	
				[An example of control board connection
CN2	Control circuit connection			
	1	GND		λщ
	2	CLK		
	3	START/S	ТОР	
	(4)	CW/CCW		
	(5)	DC5V-out	t	C1 35V 33uF
CN3	Power Input			
	1	DC24V	In—	2 VIX PWM 2 3 VIN- GND 3 4 VIN-
	2	DC24V	In +	CN-4P PWM Module

circuit]